

MODEL 260 - INCREMENTAL ENCODER



FEATURES Low Profile 1.19"

Up to 12 Pole Commutation Thru-Bore and Hollow Bore (Blind) Styles Simple, Innovative Flexible Mounting System Incorporates Opto-ASIC Technology CE Marking Available

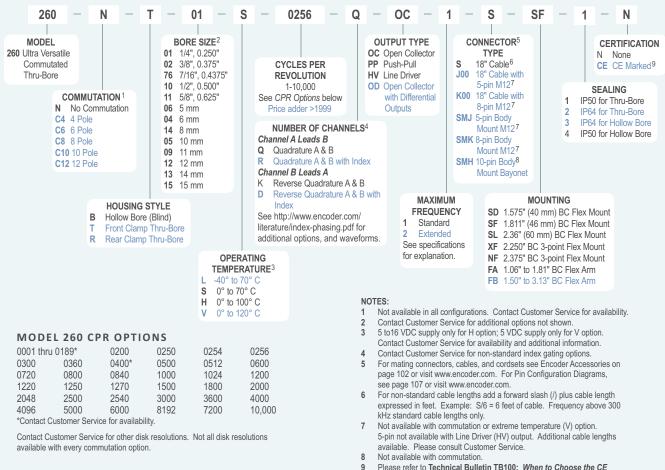
The Model 260's larger bore (up to 0.625") and low profile make it the perfect solution for many machine and motor applications. Available in two distinct formats—a Hollow Bore and a complete Thru-Bore—the Model 260 uses EPC's pioneering Opto-ASIC design. The Model 260 uses EPC's innovative anti-backlash mounting system, allowing simple, reliable, and precise encoder attachment. Unlike traditional kit or modular encoder designs, its integral bearing set provides stable and consistent operation without concerns for axial or radial shaft runout. For brushless servo motor applications, the Model 260 can be specified with three 120° electrical phase tracks to provide up to 12 pole commutation feedback. The optional extended temperature capability allows servo motors to operate at higher power outputs and duty cycles.

COMMON APPLICATIONS

Brushless Servo Motor Commutation, Robotics, Motor-Mounted Feedback, Assembly Machines, Digital Plotters, High Power Motors

MODEL 260 ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.



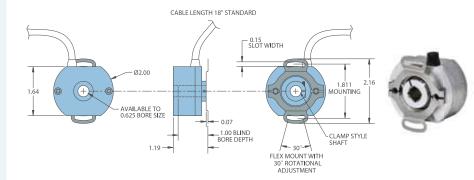
9 Please refer to Technical Bulletin TB100: When to Choose the CE Option at www.encoder.com.



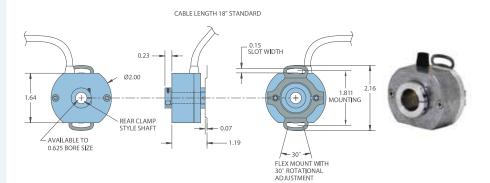
MODEL 260 SPECIFICATIONS

| Electrical | |
|----------------------|--|
| Innut Voltage | 4.75 to 28 VDC for temperatures |
| input voitagemini | up to 70° C |
| | • |
| | 5 to 16 VDC for 0° to 100° C operating |
| | temperature |
| | 5 VDC for 0° to 120° C operating |
| | temperature |
| Input Current | 100 mA max with no output load |
| | Incremental- Two square waves in |
| | quadrature with channel A leading B |
| | for clockwise shaft rotation, as viewed |
| | |
| | from the mounting face. |
| | See Waveform Diagrams. |
| Output Types | Open Collector- 20 mA max per channel |
| | Push-Pull- 20 mA max per channel |
| | Line Driver- 20 mA max per channel |
| | (Meets RS 422 at 5 VDC supply) |
| Index | Once per revolution gated to channel A. |
| macx | |
| May Francisco | See Waveform Diagrams. |
| wax. Frequency | Standard Frequency Response is |
| | 200 kHz for CPR 1 to 2540 |
| | 500 kHz for CPR 2541 to 5000 |
| | 1 MHz for CPR 5001 to 10,000 |
| | Extended Frequency Response |
| | (optional) is 300 kHz for CPR 2000, |
| | 2048, 2500, and 2540 |
| Noise Immunity | Tested to BS EN61000-6-2; BS |
| , | EN50081-2; BS EN61000-4-2; BS |
| | EN61000-4-3; |
| | |
| | BS EN61000-4-6, BS EN55011 |
| | 67.5° electrical or better is typical, |
| Edge Separation | 54° electrical minimum at temperatures |
| | > 99° C |
| Accuracy | Within 0.01° mechanical from one cycle |
| | to any other cycle, or 0.6 arc minutes. |
| Commutation | Up to 12-pole. Contact Customer |
| | Service for availability. |
| Comm. Accuracy | |
| | |
| Mechanical | |
| Max Shaft Speed | 7500 RPM. Higher shaft speeds may be |
| | achievable, contact Customer Service. |
| | Note: For extreme temperature |
| | operation, de-rate temperature by 5° C |
| | for every 1000 RPM above 3000 RPM |
| Bore Tolerance | 0.0000" / +0.0006" |
| User Shaft Tolerance | |
| | |
| Radial Runout | |
| Axial Endplay | |
| Starting Torque | IP50 Thru-Bore: 0.50 oz-in |
| | IP50 Hollow Bore: 0.30 oz-in |
| | IP64 Thru-Bore: 2.50 oz-in |
| | IP64 Hollow Bore: 2.0 oz-in |
| | Note: Add 3.0 oz-in for -40° C operation |
| Moment of Inertia | $\dots 3.9 \times 10^{-4} \text{ oz-in-sec}^2$ |
| Max Acceleration | |
| | Non-corrosive material |
| | |
| Weight | |
| Environmental | |
| Storage Temp | 40° to +100° C |
| ÷ , | 98% RH non-condensing |
| | 10 g @ 58 to 500 Hz |
| | |
| | 50 g @ 11 ms duration |
| sealing | IP50; IP64 available |
| | |

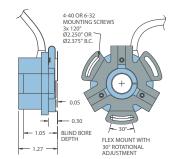
MODEL 260 WITH FRONT SHAFT CLAMP (T) WITH 1.811" (46 MM) BC SLOTTED FLEX (SF)



MODEL 260 REAR CLAMP (R) WITH 1.811" (46 MM) BC SLOTTED FLEX (SF)



THREE POINT FLEX MOUNT (XF, NF)

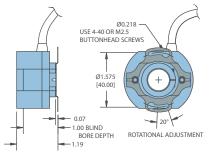




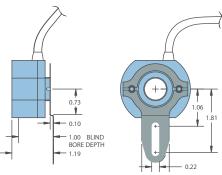
All dimensions are in inches with a tolerance of ± 0.005 " or ± 0.01 " unless otherwise specified.



1.575" (40 MM) BC FLEX MOUNT (SD)

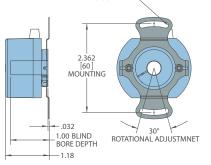


1.06" TO 1.81" FLEX ARM (FA)

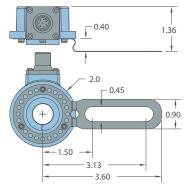


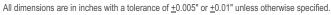
2.36" (60 MM) BC FLEX MOUNT (SL)

USE 4-40 OR M2.5 BUTTONHEAD SCREWS



1.50" TO 3.13" FLEX ARM (FB)









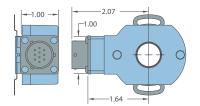




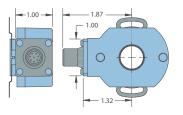


MODEL 260 CONNECTOR OPTIONS

BODY MOUNT 10-PIN BAYONET (SMH)

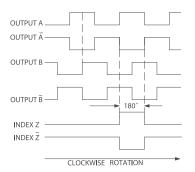


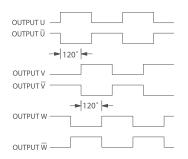
BODY MOUNT M12 (SMJ, SMK)



All dimensions are in inches with a tolerance of ± 0.005 " or ± 0.01 " unless otherwise specified.

WAVEFORM DIAGRAMS





CW ROTATION OF SHAFT AS VIEWED LOOKING AT THE ENCODER FACE. NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. WWEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS Ä, B, Ž FOR HV AND OD OUTPUTS ONLY.

WIRING TABLE

| Function | Cable [†] Wire Color | 5-pin M12** | 8-pin M12** | 10-pin Bayonet ⁺ |
|----------|----------------------------------|----------------|----------------|--------------------------------|
| Com | Black | 3 | 7 | F |
| +VDC | White | 1 | 2 | D |
| А | Brown | 4 | 1 | А |
| A' | Yellow | | 3 | Н |
| В | Red | 2 | 4 | В |
| В' | Green | | 5 | J |
| Z | Orange | 5 | 6 | С |
| Ζ' | Blue | | 8 | К |
| U | Violet | | | |
| U' | Gray | | | |
| V | Pink | | | |
| V' | Tan | | | |
| W | Red/Green | | | |
| W' | Red/Yellow | | | |
| Shield | Bare* | | | |

*CE Option: Cable shield (bare wire) is connected to internal case.

**Non-CE Option: Cable shield is connected to M12 connector body.

CE Option: Cable shield and M12 connector body is connected to internal case.

+CE Option: Pin G is connected to internal case.

[†]Standard cable for non-commutated models is 24 AWG For commutated units, conductors are 28 AWG.